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A simple span selector for periodogram smoothing

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SUMMARY

One approach to estimating the spectral density of a stationary time series is to smooth the periodogram and one important component of this approach is the choice of the span for smoothing. This note proposes a new span selector which is based on unbiased risk estimation. The proposed span selector is simple, and does not impose strong conditions on the unknown spectrum. For example, it does not require the unknown spectrum to possess a second derivative, which is a typical requirement of most plug-in type or spline-based methods. The finite sample performance of the proposed span selector is illustrated via a small simulation.

Some key words: Bandwidth/span selection; Spectral density estimation; Unbiased risk estimation.

1. INTRODUCTION

Let \( \{x_t\} \) \( (t = 0, \pm 1, \pm 2, \ldots) \) be a real-valued, zero mean stationary process with autocovariance function \( \gamma_r = E(x_{t-r} x_t) \) \( (r = 0, 1, \ldots) \) and spectral density

\[
f(\omega) = \frac{1}{2\pi} \sum_{r} \gamma_r \exp(-i\omega r), \quad \omega \in [0, 2\pi).
\]

Suppose from one realisation of \( \{x_t\} \) we observe \( x_0, \ldots, x_{n-1} \) and compute the periodogram

\[
I(\omega) = \frac{1}{2\pi n} \sum_{t=0}^{n-1} x_t \exp(-i\omega t), \quad \omega \in [0, 2\pi).
\]

Then the spectral density \( f(\omega) \) can be estimated nonparametrically by applying weighted local smoothing to the periodogram. To simplify notation, let \( \omega_j = 2\pi j/n \) and denote \( I(\omega_j) \) and \( f(\omega_j) \) by \( I_j \) and \( f_j \), respectively, for \( j = 0, \ldots, n-1 \). The smoothed periodogram estimator \( \hat{f}_j \) of \( f_j \) is

\[
\hat{f}_j = \sum_{k=-p}^{p} w_{p,k} I_{j+k} \quad (j = 0, \ldots, n-1),
\]

where \( 2p + 1 \) is the span for smoothing and \( w_{p,k} \) \( (k = -p, \ldots, p) \) are nonnegative weights satisfying

\[
w_{p,k} = w_{p,-k} \quad (k = 1, \ldots, p), \quad \sum_{k=-p}^{p} w_{p,k} = 1.
\]

The weight \( w_{p,0} \) should also be a decreasing function of \( p \). These conditions are satisfied by almost all suitably discretised kernel functions commonly used for smoothing. Since the spectral density is periodic with period \( 2\pi \), periodic smoothing is used in (1) to handle boundary effects. That is, define \( I_{-1} = I_{n-1}, I_0 = I_0 \) and so on. Fan (1992) demonstrated that weighted local linear regression is superior to the kernel type estimator (1) as it (i) adapts to different types of design, and (ii) does not require boundary modifications. However, in the present situation estimator (1) is expected to give similar performance as the data \( (I_0, \ldots, I_{n-1}) \) are equally spaced and boundary effects are handled by periodic smoothing. The parameter \( p \) plays the same role as the bandwidth in the nonparametric density and curve estimation contexts.
Here we propose an automatic method, based on unbiased risk estimation, for estimating the \( p \) which minimises the risk function
\[
R(p) = \frac{1}{n} E \left\{ \sum_{j=0}^{n-1} (f_j - \hat{f}_j)^2 \right\}. 
\]
(3)

Two other widely-used and locally equivalent risk functions are
\[
R'(p) = \frac{1}{n} E \left\{ \sum_{j=0}^{n-1} (\log f_j - \log \hat{f}_j)^2 \right\}, \quad R''(p) = \frac{1}{n} E \left\{ \sum_{j=0}^{n-1} \left( \frac{\hat{f}_j - f_j}{f_j} \right)^2 \right\}. 
\]
(4)

However, with \( R(p) \) the unknown spectral density \( f \) is not required to be strictly positive, i.e. zero values are allowed. Also, in the, as yet, unpublished paper ‘Nonparametric estimation and simulation of two-dimensional Gaussian image textures’ by T. C. M. Lee and M. Berman, it is shown that, in the context of image texture synthesis, \( R(p) \) is the preferred risk function.

Nonparametric spectral density estimators other than (1) have been proposed in the literature. The windowed autocovariance estimator was one of the first. More recently, Wahba (1980) applied a cubic smoothing spline to smooth the log-periodogram. Chow & Grenander (1985) and Pawitan & O’Sullivan (1994) used a penalised Whittle likelihood approach, and Cameron (1987) developed some partitioning algorithms to approximate the spectral density by a step function. Hannan & Rissanen (1988) constructed a criterion based on the stochastic complexity for periodogram smoothing. Moulin (1994) applied wavelet thresholding techniques for log-periodogram smoothing, and Fan & Gijbels (1996, Ch. 6) describe unpublished work of J. Fan and E. Kreuzberger, in which they used local polynomial smoothers developed in Fan & Gijbels (1995) to smooth the periodogram and the log-periodogram. These authors also fitted the local Whittle likelihood for estimating the spectral density. Riedel & Sidorenko (1996) combined multiple tapering and plug-in techniques for adaptively smoothing the log-periodogram.

2. UNBIASED RISK ESTIMATION

2.1. Background and cross-validation

If all moments of \( x_r \) exist, the sum of all \(|y_i|\)'s is bounded and \( n \) is large (Brillinger, 1981, Theorem 5.2.6), then
\[
I_j = f_j \varepsilon_j \quad (j = 0, \ldots, n - 1),
\]
(5)

where \( \varepsilon_0 \) and \( \varepsilon_n \) if \( n \) is even, are independent \( \chi^2 \) random variables, and all other \( \varepsilon_j \)'s are independent random variables distributed as the standard exponential distribution. If \( n \) is small, the data can be tapered in order to reduce the bias of the periodogram, and (5) remains approximately valid (Brillinger, 1981, Ch. 5). From now on, as in Moulin (1994) and Pawitan & O’Sullivan (1994), \( \varepsilon_0 \) and \( \varepsilon_n \) will be treated as if they were standard exponential random variables and the approximation in (5) is assumed to be exact. The effect of these changes is asymptotically negligible. Hence we have the following model:
\[
I_j = f_j \varepsilon_j \quad (j = 0, \ldots, n - 1),
\]
(6)

where \( \varepsilon_j \) are independent standard exponential random variables. Note that \( E(\varepsilon_j) = \text{var}(\varepsilon_j) = 1 \) and \( E(\varepsilon_j^2) = 2 \).

Since \( R(p) \) is unknown, a natural approach to finding its minimiser is to form an unbiased estimator of \( R(p) \) and choose \( p \) to minimise it. In a cross-validation method, which is presented in an unpublished report of F. Palmer and is mentioned in Hurvich (1985), \( p \) is chosen to be the minimiser \( p_{CV} \) of the cross-validation score
\[
CV(p) = \frac{1}{n} \sum_{j=1}^{n} (I_j - \hat{f}_{-i,j})^2 = \frac{RSS}{n(1 - w_{p,0})^2},
\]
(7)
where \( \hat{f}_j \) is the usual ‘leave-one-out’ estimate for \( f_j \) and \( \text{rss} = \sum (I_j - \hat{f}_j)^2 \) is the residual sum of squares. The last equality of (7) can be obtained by using equation (3) of Hurvich (1985). It is straightforward to show that \( \text{cv}(p) \) is biased for \( R(p) \) when \( n \) is finite. Since, for low-dimensional parameter estimation problems, biased estimators can lead to serious estimation errors, we seek an unbiased estimator for \( R(p) \).

2.2. The proposed span selector

We begin by calculating \( E(\text{rss}) = E[I_j^2 - 2I_j\hat{f}_j + \hat{f}_j^2] \). Since the \( \epsilon_j \) are independent standard exponentials, then \( E(I_j) = f_j \), \( E(\hat{f}_j^2) = E(f_j^2\epsilon_j^2) = 2f_j^2 \) and

\[
E(I_j\hat{f}_j) = E\left(f_j \epsilon_j \sum_{k=-p}^p w_{p,k} f_j \epsilon_j \right) = E\left(\sum_{k=0}^p w_{p,k} f_j^2 \epsilon_j^2 + \sum_{k=p}^{0} w_{p,k} f_j \epsilon_j \hat{f}_j \epsilon_j \right)
\]

\[
= 2f_j^2 + f_j \sum_{k=0}^p w_{p,k} f_j \epsilon_j + f_j \sum_{k=-p}^{0} w_{p,k} f_j \epsilon_j = 1\text{w}_{p,o} f_j^2 + f_j E(\hat{f}_j).
\]

Therefore,

\[
E(I_j - \hat{f}_j)^2 = 2f_j^2 - 2\{w_{p,o} f_j^2 + f_j E(\hat{f}_j)\} + E(\hat{f}_j^2) = E(f_j - \hat{f}_j)^2 + (1 - 2w_{p,o}) f_j^2,
\]

\[
E(\text{rss}) = nR(p) + (1 - 2w_{p,o}) E\left(\sum_{j=0}^{n-1} I_j^2\right).
\]

Thus

\[
R(p) = \frac{\text{rss}}{n} - \frac{(1 - 2w_{p,o})}{2n} \sum_{j=0}^{n-1} I_j^2
\]

is an unbiased estimator of \( R(p) \). We propose to choose the minimiser \( p_{\text{opt}} \) of \( \hat{R}(p) \) as the span.

This idea of unbiased risk estimation has been used for bandwidth selection in the nonparametric curve estimation context (Rice, 1984; Chiu, 1990) and has its origin in Mallows’ \( C_p \) (Mallows, 1973), but it has not been applied to nonparametric spectral estimation. The crucial difference in the present context is that the variance of the noise variables \( \epsilon_j \) is known.

2.3. Log-periodogram smoothing

Unbiased risk estimation can also be applied to choose the span for log-periodogram smoothing. In this case it is natural to use \( R'(p) \) defined by (4), and the first step is to transform the multiplicative model (6) into an additive model by taking a logarithmic transform:

\[
y_j = \log I_j + \psi(1) + \log f_j + \xi_j \quad (j = 0, \ldots, n - 1),
\]

where \( \xi_j \) are independent zero mean random variables with variance \( \pi^2/6 \), and \( \psi(x) \) is the digamma function with \( \psi(1) = 0.57722 \); see Wahba (1980), in which a cubic smoothing spline was applied to smooth the \( y_j \)'s, with smoothing parameter chosen by generalised cross-validation. Using the same technique as before, one can show that

\[
\hat{R}'(p) = \frac{1}{n} \sum_{j=0}^{n-1} \left(y_j - \hat{g}_j\right)^2 - \frac{(1 - 2w_{p,o})\pi^2}{6n}
\]

is an unbiased estimator of \( R'(p) \). Here \( \hat{g}_j = \sum w_{p,k} y_{j+k} \) is the estimate of \( \log f_j \). Thus one can choose the minimiser of \( \hat{R}'(p) \) as the span for log-periodogram smoothing.
3. Simulation

A simulation was conducted to evaluate the relative finite sample performance of the proposed span selector \( p_{ER} \) and the cross-validation based selector \( p_{CV} \). The weights \( w_{p,k} \)'s in (1) used for this simulation study were

\[
 w_{p,k} = w_{p,k}^{'} \left( \sum_{k=-p}^{p} w_{p,k}^{'} \right)^{-1}, \quad w_{p,k}^{'} = \frac{3}{4p} \left( 1 - \frac{k^2}{p^2} \right) \quad (k = -p, \ldots, p).
\]

These weights are a discrete version of the optimal kernel of order \((0, 2)\) derived in Gasser, Müller & Mammitzsch (1985). They minimise the asymptotic optimal risk, and it is easy to verify that they satisfy conditions (2).

Four different test examples from the ARMA \((\alpha, \beta)\) model

\[
 x_t + a_1 x_{t-1} + \ldots + a_p x_{t-p} = \tau_t + b_1 \tau_{t-1} + \ldots + b_\beta \tau_{t-\beta}, \quad \tau_t \sim N(0, 1)
\]

were used: Example 1 was AR \((3)\) with \( a_1 = -1.5, a_2 = 0.7 \) and \( a_3 = -0.1 \); Example 2 was MA \((4)\) with \( b_1 = -0.3, b_2 = -0.6, b_3 = -0.3 \) and \( b_4 = 0.6 \); Example 3 was AR \((3)\) with \( a_1 = 0.9, a_2 = 0.8 \) and \( a_3 = 0.6 \); and Example 4 was MA \((3)\) with \( b_1 = 0.9, b_2 = 0.8 \) and \( b_3 = 0.6 \). Examples 1 and 2 were used by Fan & Gijbels (1996, Ch. 6), Pawitan & O'Sullivan (1994) and Wahba (1980), and Examples 3 and 4 were used by Hurvich (1985).

For each example 200 independent series were simulated with \( n = 256 \), and for each series we computed the optimal risk \( R_{opt} = \min_{p} R(p) \) and the risks \( R(p_{CV}) \) and \( R(p_{ER}) \) using (3). We also computed the two risk-ratios \( r_{CV} = R(p_{CV})/R_{opt} \) and \( r_{ER} = R(p_{ER})/R_{opt} \). The values of the average risk-ratio differences \( (r_{CV} - r_{ER}) \) for Examples 1 to 4 respectively were \(-0.0083, 0.1505, 0.1533 \) and \(-0.0479, 0.0862, 0.0393 \) and \(0.4296\): the 200 simulations were insufficient to discriminate statistically between the two selectors for Examples 1 and 2, while for Examples 3 and 4 there is strong evidence that \( p_{ER} \) outperformed \( p_{CV} \).

Acknowledgement

This work is part of the author's PhD thesis. He would like to express his gratitude to his supervisors, Mark Berman and Vic Solo, for their continuous encouragement, guidance and patience. He would also like to thank a referee, an associate editor and the editor for valuable comments, which have led to this more succinct version of the paper.

References


[Received February 1996. Revised June 1997]